

Amendments to the Claims:

Claim 1 is cancelled. Claims 2 to 6, 8 and 9 are amended and claim 19 is added as set forth hereinafter.

Listing of Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application.

1. (Cancelled).
2. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein, when forming said ~~desired~~ required value, the method comprises the further step of considering said desired ~~value input~~ quantities quantity prescriptions starting with the desired ~~value~~ input quantity prescription having the lowest priority.
3. (Currently Amended) The method of ~~claim 1~~ claim 19, comprising the further step of coupling said desired ~~value input~~ quantities quantity prescription to different priorities, respectively.
4. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein said desired ~~value input~~ quantities quantity prescriptions limit said desired value or shift said desired value by an additive amount.

5. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein a priority is permanently assigned to each one of said desired ~~value input quantities~~ quantity prescriptions.

6. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein a priority is variably assigned to each one of said desired ~~value input quantities~~ quantity prescriptions.

7. (Original) The method of claim 6, wherein said priorities are assigned in dependence upon the operating state of said vehicle.

8. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein different types of desired ~~value input quantities~~ quantity prescriptions are considered by different modules; and, the same types of desired ~~value input quantities~~ quantity prescriptions are each considered by a single module for forming said desired value.

9. (Currently Amended) The method of ~~claim 1~~ claim 19, wherein a desired torque is selected as said desired ~~value~~ quantity prescription.

10. (Previously Presented) A method for controlling a drive unit of a vehicle, the method comprising the steps of:

adjusting an output quantity of said drive unit in dependence upon desired quantity prescriptions;

5 assigning a priority to each of said desired quantity

prescriptions; and,

to make the adjustment of said output quantity, forming a desired quantity which considers said desired quantity prescriptions in a sequence of their priorities.

11. (Previously Presented) The method of claim 10, wherein, when forming said desired quantity, the method comprises the further step of considering said desired quantity prescriptions starting with the desired quantity prescription having the lowest
5 priority.

12. (Previously Presented) The method of claim 10, comprising the further step of coupling said desired quantity prescriptions to different priorities, respectively.

13. (Previously Presented) The method of claim 10, wherein said desired quantity prescriptions limit said desired quantity or shift said desired quantity by an additive amount.

14. (Previously Presented) The method of claim 10, wherein a priority is permanently assigned to each one of said desired quantity prescriptions.

15. (Previously Presented) The method of claim 10, wherein a priority is variably assigned to each one of said desired quantity prescriptions.

16. (Previously Presented) The method of claim 15, wherein said

priorities are assigned in dependence upon the operating state of said vehicle.

17. (Previously Presented) The method of claim 10, wherein different types of desired quantity prescriptions are considered by different modules; and, the same types of desired quantity prescriptions are each considered by a single module for forming
5 said desired quantity.

18. (Previously Presented) The method of claim 10, wherein a desired torque is selected as said desired quantity.

19. (New) A method for controlling a drive unit of a vehicle, the method comprising the steps of:

receiving desired quantity prescriptions for an output quantity of said drive unit;

5 assigning a priority to each of said desired quantity prescriptions;

coordinating said desired quantity prescriptions in a time sequence in dependence upon their respective priorities to form a resulting desired quantity prescription as a required value for
10 said output quantity; and,

adjusting said required value for said output quantity.